HPCS Application Analysis and Assessment

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Abstract

The value of a HPC system to a user includes many factors, such as: execution time on a particular problem, software development time, and both direct and indirect costs. The DARPA High Productivity Computing Systems is focused on providing a new generation of economically viable high productivity computing systems for the national security and industrial user community in the 2007-2010 timeframe. The goal is to provide systems that double in productivity (or value) every 18 months. This program has initiated a fundamental reassessment of how we define and measure performance, programmability, portability, robustness and ultimately productivity in the HPC domain. This talk will describe the HPCS efforts to develop a productivity assessment framework (see Figure 1), characterize HPC user workflows, and define the scope of the target applications.

Introduction

The HPCS program seeks to create trans-Pefaflop systems of significant value to the Government HPC community. Such value will be determined by assessing many additional factors beyond just theoretical peak flops (i.e. "Machoflops"). Ultimately, the goal is to decrease the time-to-solution, which means decreasing both the execution time and development time of an application on a particular system. Evaluating the capabilities of a system with respect to these goals requires a different assessment process. The goal of the HPCS assessment activity is to prototype and baseline a process that can be transitioned to the acquisition community for 2010 procurements.

Development Time

The most novel part of the assessment activity will be the effort to measure/predict the ease or difficulty of developing HPC applications. Currently, there is no quantitative methodology for comparing the development time impact of various HPC programming technologies. To achieve this goal, we will use a variety of tools including
- Application of code metrics on existing HPC codes
- Several prototype analytic models of development time
- Interface characterization (e.g. language, parallel model, memory model, …)
- Scalable benchmarks designed for testing both performance and programmability
- Classroom software engineering experiments
- Human validated demonstrations

These tools will provide the baseline data necessary for modeling development time and allow the new technologies developed under HPCS to be assessed quantitatively.

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Execution Time

The execution time part of the assessment activity will leverage the strong heritage in the HPC performance modeling community. This will include analytic, source code, and executable based tools for analyzing the projected performance of various applications on current, next generation and HPCS designs. The execution time and development time activities will be strongly coupled so as to provide a clear picture to the community of the tradeoffs that exist between execution time and development time.
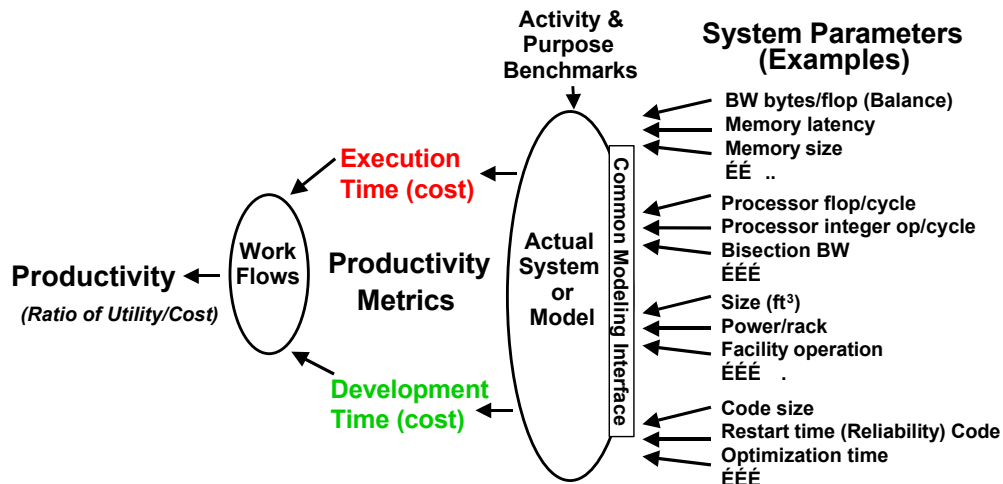
Figure 1: HPCS Assessment Framework. The goal of the framework is to provide a mechanism for integrating system specific capabilities with user specific needs to assess the value of a particular machine for a particular mission.

HPCS Application Analysis and Assessment

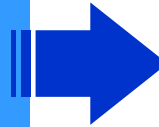**Dr. Jeremy Kepner / Lincoln**

Dr. David Koester / MITRE

- **Introduction** → • *Motivation*
  - *Productivity Framework*

- **Workflows**

- **Metrics**
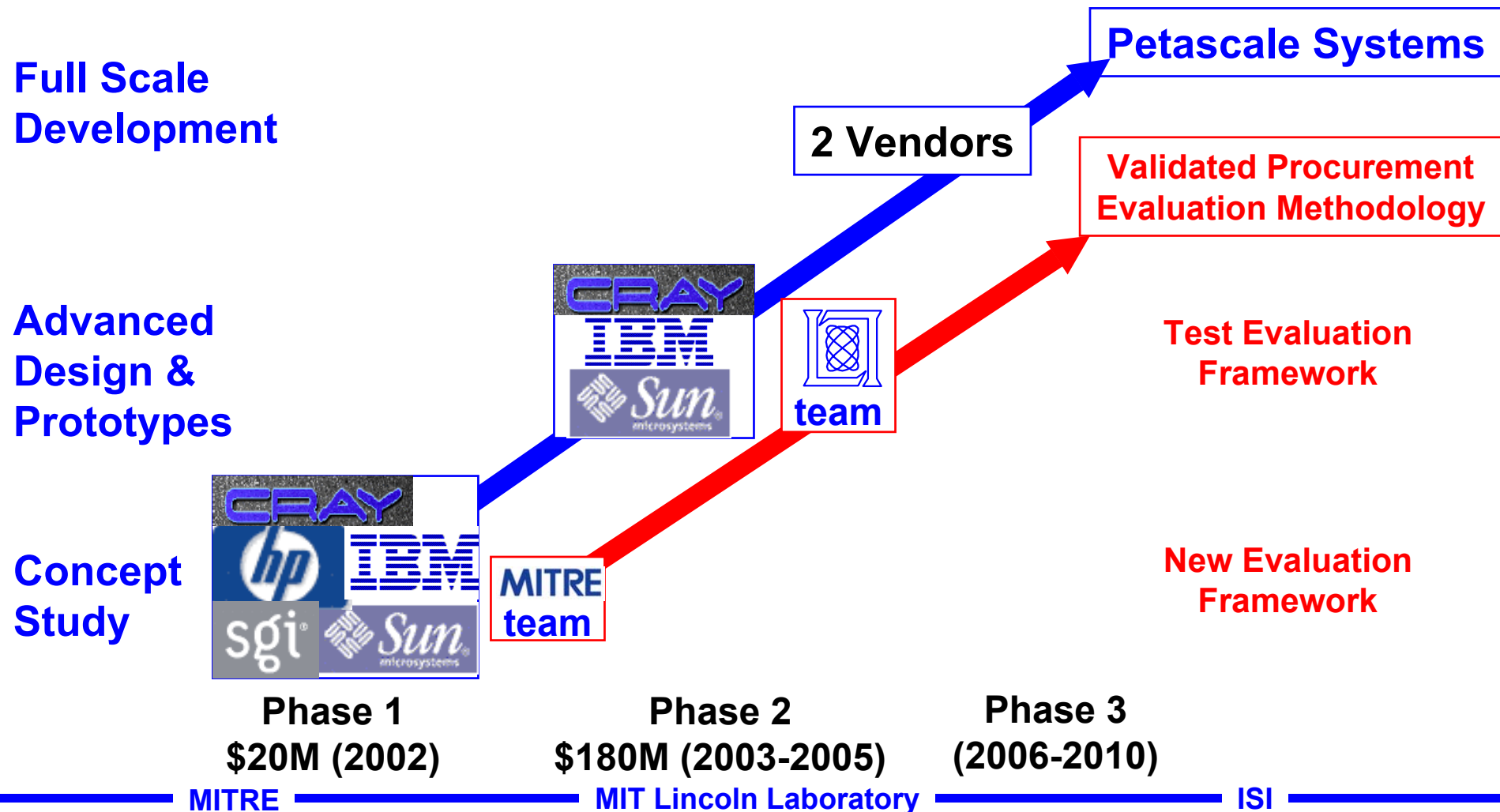
- **Models & Benchmarks**

- **Schedule and Summary**

High Productivity Computing Systems
-Program Overview-

➢ **Create a new generation of economically viable computing systems and a procurement methodology for the security/industrial community (2007 – 2010)**

Petascale Systems

Full Scale Development

2 Vendors

Validated Procurement Evaluation Methodology

Advanced Design & Prototypes

CRAY
IBM
Sun microsystems

team

Test Evaluation Framework

Concept Study

CRAY
hp
IBM
sgi
Sun microsystems

MITRE team

New Evaluation Framework

Phase 1
$20M (2002)

Phase 2
$180M (2003-2005)

Phase 3
(2006-2010)

MITRE ━━━ MIT Lincoln Laboratory ━━━ ISI

Execution Time (Example)

Low

Large FFTs
(Reconnaissance)

Table Toy (GUPS)
(Intelligence)

Adaptive Multi-Physics
Weapons Design
Vehicle Design
Weather

HPCS

Spatial Locality

Top500 Linpack
Rmax

StreamsAdd

High

High   **Temporal Locality**   Low

Development Time (Example)

High

Matlab/
Python

High Performance
High Level Languages

UPC/CAF

Language Expressiveness

C/Fortran
MPI/OpenMP

SIMD/
DMA

Assembly/
VHDL

Low

Low   **Language Performance**   High

Tradeoffs

Current metrics favor caches and pipelines

- **Systems ill-suited to applications with**
- **Low spatial locality**
- **Low temporal locality**

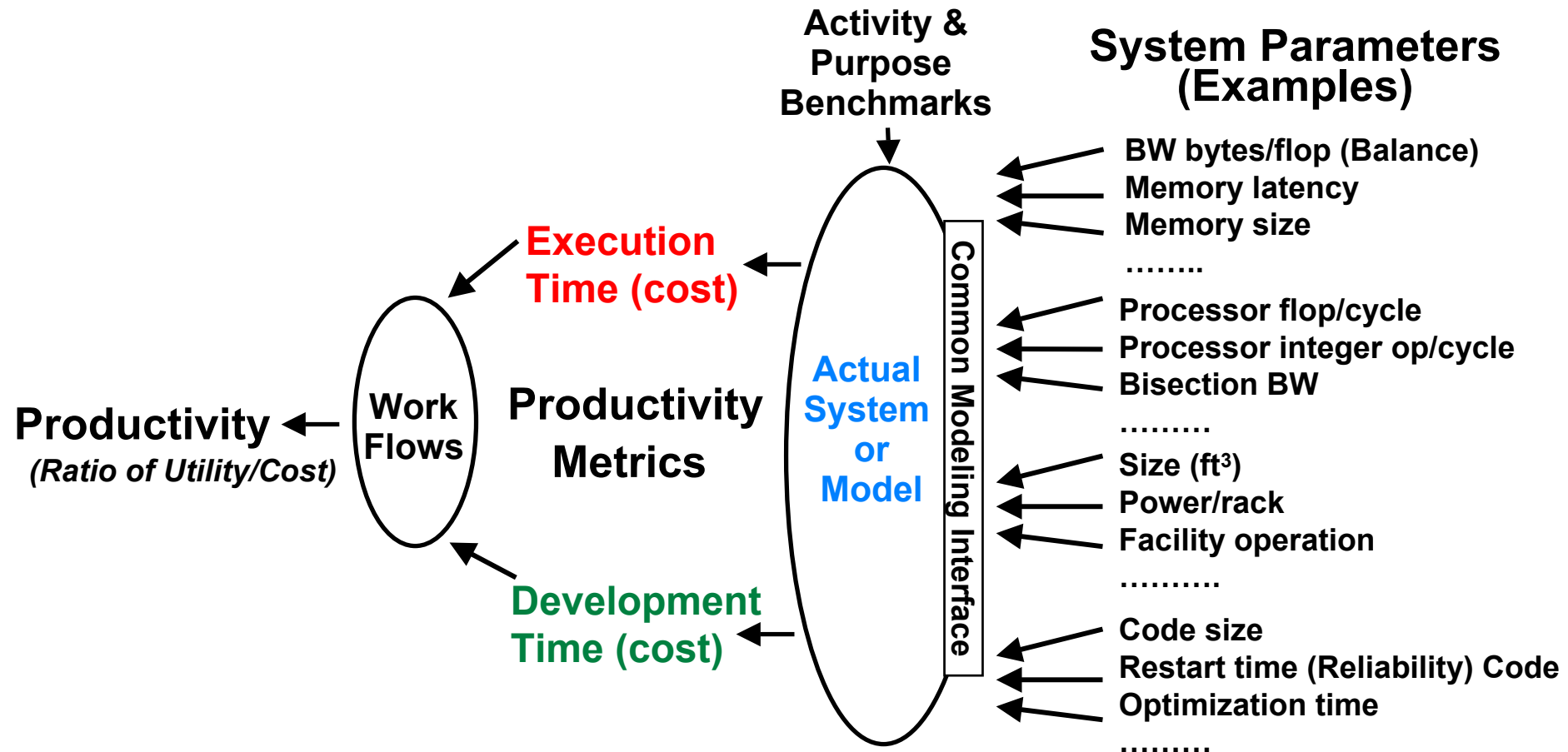**No metrics widely used**

- **Least common denominator standards**
- **Difficult to use**
- **Difficult to optimize**

- **HPCS needs a validated assessment methodology that values the "right" vendor innovations**
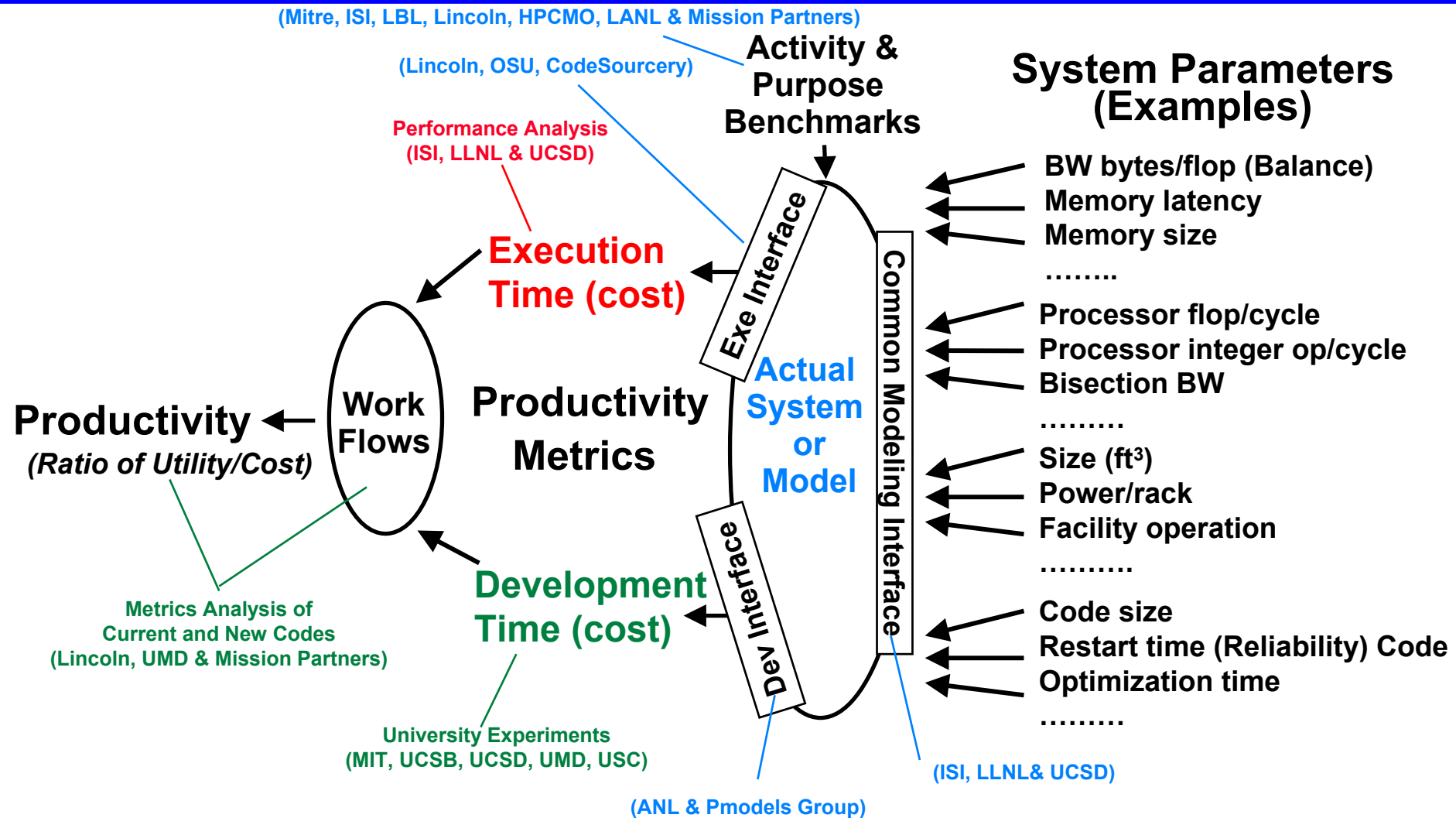- **Allow tradeoffs between Execution and Development Time**

Activity & Purpose Benchmarks

System Parameters (Examples)

- BW bytes/flop (Balance)
- Memory latency
- Memory size
- ……..

- Processor flop/cycle
- Processor integer op/cycle
- Bisection BW
- ………

- Size (ft^3)
- Power/rack
- Facility operation
- ……….

- Code size
- Restart time (Reliability) Code
- Optimization time
- ………

Execution Time (cost)

Actual System or Model

Common Modeling Interface

Productivity

(Ratio of Utility/Cost)

Work Flows

Productivity Metrics

Development Time (cost)

Phase 2: Implementation

System Parameters (Examples)

(Mitre, ISI, LBL, Lincoln, HPCMO, LANL & Mission Partners)

(Lincoln, OSU, CodeSourcery)

Activity & Purpose Benchmarks

Performance Analysis
(ISI, LLNL & UCSD)

Execution Time (cost)

Productivity Metrics

Actual System or Model

Exe Interface

Common Modeling Interface

Dev Interface

BW bytes/flop (Balance)
Memory latency
Memory size
……..

Processor flop/cycle
Processor integer op/cycle
Bisection BW
………

Size (ft³)
Power/rack
Facility operation
……….

Code size
Restart time (Reliability) Code
Optimization time
………

Work Flows

Productivity
(Ratio of Utility/Cost)

Metrics Analysis of
Current and New Codes
(Lincoln, UMD & Mission Partners)

Development Time (cost)

University Experiments
(MIT, UCSB, UCSD, UMD, USC)

(ANL & Pmodels Group)

(ISI, LLNL& UCSD)

MITRE   MIT Lincoln Laboratory   ISI

Outline

- **Introduction**

- **Workflows** →
  - *Lone Researcher*
  - *Enterprise*
  - *Production*

- **Metrics**

- **Models & Benchmarks**

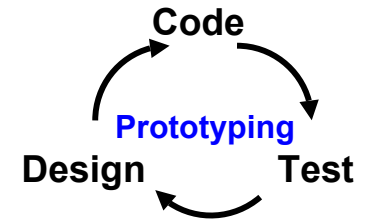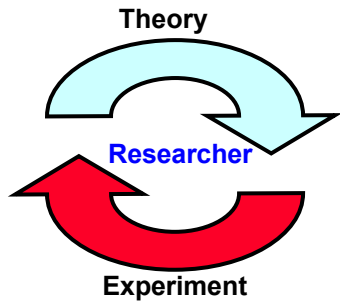- **Schedule and Summary**

HPCS Mission Work Flows

Overall Cycle — **Development Cycle**

Researcher

Days to hours — Hours to minutes

Theory
Researcher
Experiment

- Development
- Execution

Code
Prototyping
Design — Test

Enterprise

Months to days — Months to days

Visualize — Design
Enterprise
Port Legacy Software
Simulation

Port Legacy Software → Code — Optimize
Prototyping — Development
Design — Test — Scale

Production

Hours to Minutes (Response Time) — Years to months

Observe — Orient
Production
Initial Product Development
Act — Decide

Initial Development
Design
Code
Test
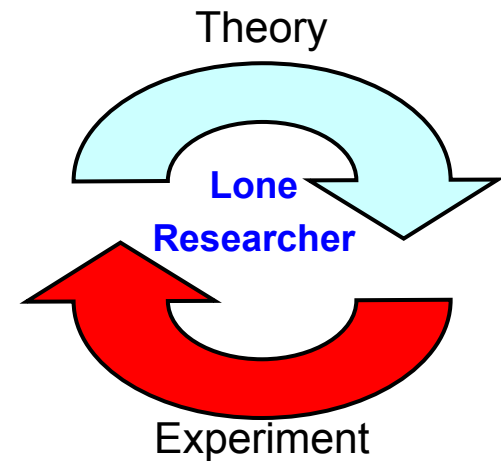Port, Scale, Optimize
Evaluation
Maintenance
Operation

HPCS Productivity Factors: Performance, Programmability, Portability, and Robustness are very closely coupled with each work flow

Lone Researcher

- **Missions (development): Cryptanalysis, Signal Processing, Weather, Electromagnetics**

- **Process Overview**
  - **Goal: solve a compute intensive domain problem: crack a code, incorporate new physics, refine a simulation, detect a target**
  - **Starting point: inherited software framework (~3,000 lines)**
  - **Modify framework to incorporate new data (~10% of code base)**
  - **Make algorithmic changes (~10% of code base); Test on data; Iterate**
  - **Progressively increase problem size until success**
  - **Deliver: code, test data, algorithm specification**

- **Environment overview**
  - **Duration: months   Team size: 1**
  - **Machines: workstations (some clusters), HPC decreasing**
  - **Languages: FORTRAN, C → Matlab, Python**
  - **Libraries: math (external) and domain (internal)**

- **Software productivity challenges**
  - **Focus on rapid iteration cycle**
  - **Frameworks/libraries often serial**
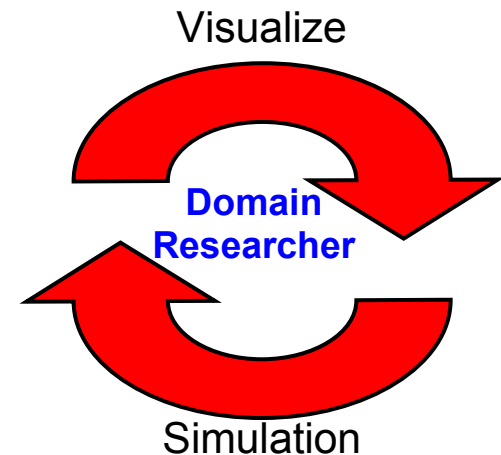
Theory

Lone Researcher

Experiment

Domain Researcher (special case)

- **Scientific Research: DoD HPCMP Challenge Problems, NNSA/ASCI Milestone Simulations**

- **Process Overview**
  - **Goal: Use HPC to perform Domain Research**
  - **Starting point: Running code, possibly from an Independent Software Vendor (ISV)**
  - **NO modifications to codes**
  - **Repeatedly run the application with user defined optimization**

- **Environment overview**
  - **Duration: months**   **Team size: 1-5**
  - **Machines: workstations (some clusters), HPC**
  - **Languages: FORTRAN, C**
  - **Libraries: math (external) and domain (internal)**

- **Software productivity challenges — None!**
- **Productivity challenges**
  - **Robustness (reliability)**
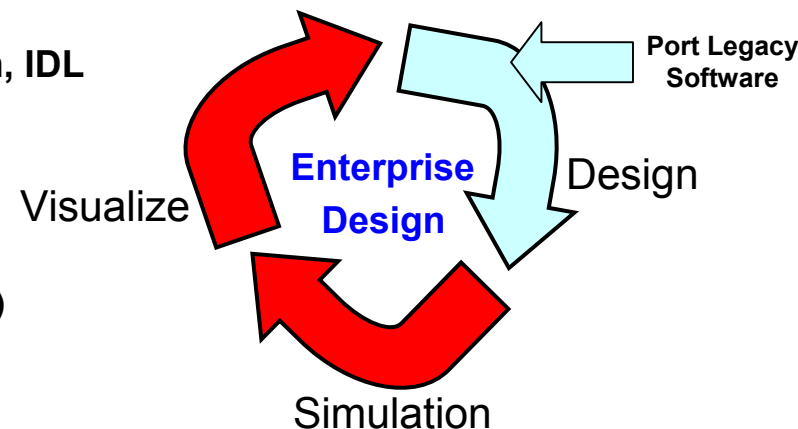 - **Performance**
  - **Resource center operability**

Visualize

Domain Researcher

Simulation

Enterprise Design

- **Missions (development): Weapons Simulation, Image Processing**

- **Process Overview**
    - **Goal: develop or enhance a system for solving a compute intensive domain problem: incorporate new physics, process a new surveillance sensor**
    - **Starting point: software framework (~100,000 lines) or module (~10,000 lines)**
    - **Define sub-scale problem for initial testing and development**
    - **Make algorithmic changes (~10% of code base); Test on data; Iterate**
    - **Progressively increase problem size until success**
    - **Deliver: code, test data, algorithm specification, iterate with user**

- **Environment overview**
    - **Duration: ~1 year   Team size: 2-20**
    - **Machines: workstations, clusters, hpc**
    - **Languages: FORTRAN, C, → C++, Matlab, Python, IDL**
    - **Libraries: open math and communication libraries**

- **Software productivity challenges**
    - **Legacy portability essential**
        - **Avoid machine specific optimizations (SIMD, DMA, …)**
    - **Later must convert high level language code**

Port Legacy Software

Enterprise Design

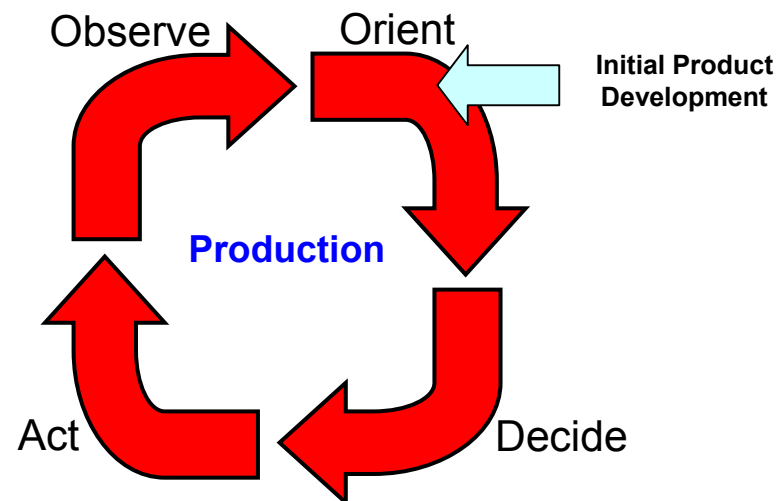Design

Visualize

Simulation

Production

- **Missions (production): Cryptanalysis, Sensor Processing, Weather**

- **Process Overview**
  - **Goal: develop a system for fielded deployment on an HPC system**
  - **Starting point: algorithm specification, test code, test data, development software framework**
  - **Rewrite test code into development framework; Test on data; Iterate**
  - **Port to HPC; Scale; Optimize (incorporate machine specific features)**
  - **Progressively increase problem size until success**
  - **Deliver: system**

- **Environment overview**
  - **Duration: ~1 year   Team size: 2-20**
  - **Machines: workstations and HPC target**
  - **Languages: FORTRAN, C, $\rightarrow$ C++**

- **Software productivity challenges**
  - **Conversion of higher level languages**
  - **Parallelization of serial library functions**
  - **Parallelization of algorithm**
  - **Sizing of HPC target machine**

Observe   Orient

Initial Product Development

Production

Act   Decide

HPC Workflow SW Technologies

Production Workflow

- **Many technologies targeting specific pieces of workflow**
- **Need to quantify workflows (stages and % time spent)**
- **Need to measure technology impact on stages**

	Workstation			Supercomputer	
Algorithm Development	Spec	Design, Code, Test		Port, Scale, Optimize	Run

Operating Systems				Linux		RT Linux
Compilers	Matlab		Java	C++	OpenMP	F90	UPC Coarray
Libraries		CORBA		VSIPL ||VSIPL++	MPI DRI	ATLAS, BLAS, FFTW, PETE, PAPI
Tools	UML		Globus		TotalView	
Problem Solving Environments		CCA		ESMF	POOMA PVL	

_____   _____

Mainstream Software   **HPC Software**

Workflow Breakdown (NASA SEL)

	Analysis and Design	Coding and Auditing	Checkout and Test
Sage	39%	14%	47%
NTDS	30	20	50
Gemini	36	17	47
Saturn V	32	24	44
OS/360	33	17	50
TRW Survey	46	20	34

Testing Techniques (UMD)

Code Reading
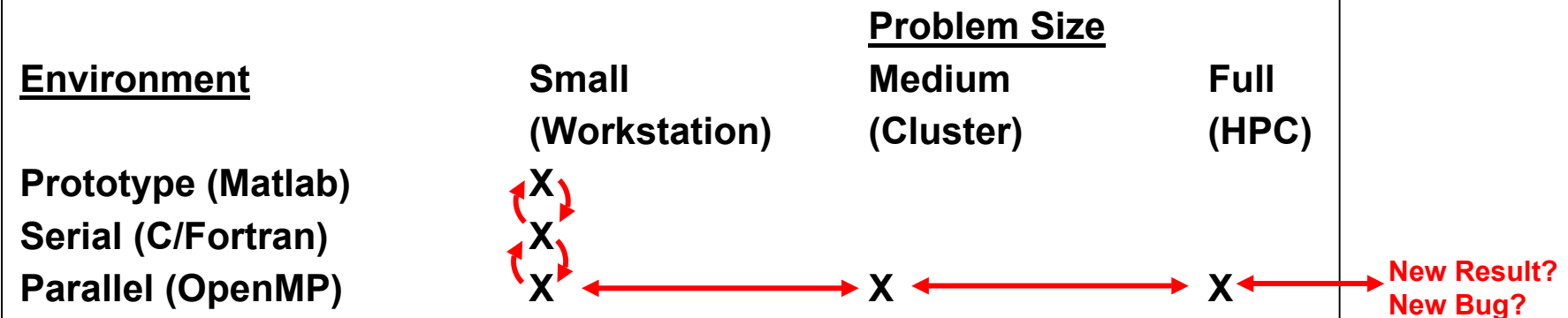Reading by Stepwise Abstraction
Functional Testing
Boundary Value Equivalence Partition Testing
Structural Testing
Achieving 100% statement coverage
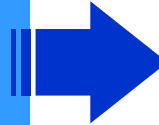
What is HPC testing process?

Problem Size

Environment	Small (Workstation)	Medium (Cluster)	Full (HPC)	
Prototype (Matlab)	X			
Serial (C/Fortran)	X			
Parallel (OpenMP)	X	X	X	New Result? New Bug?

Outline

- **Introduction**

- **Workflows**

- **Metrics**
  - *Existing Metrics*
  - *Dev. Time Experiments*
  - *Novel Metrics*
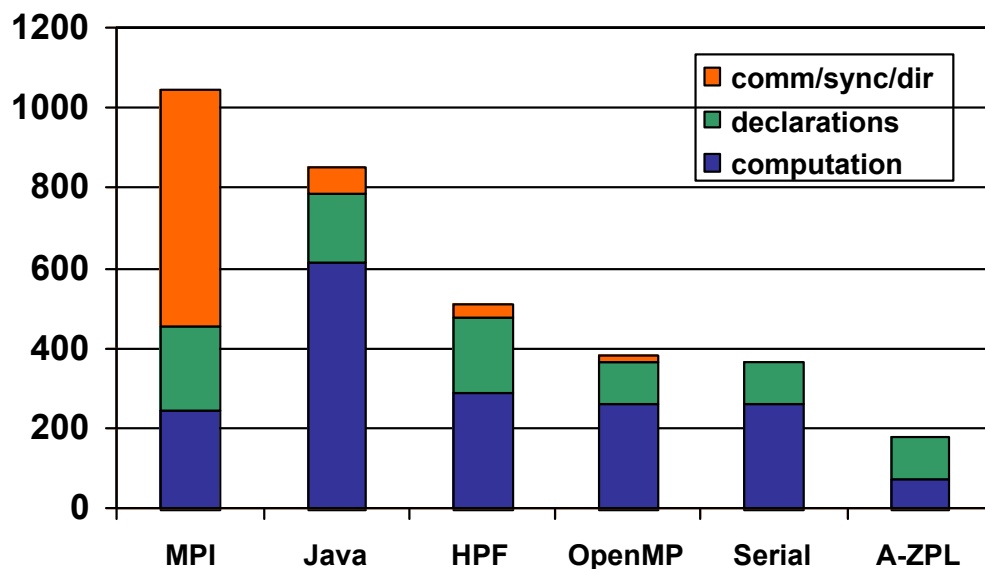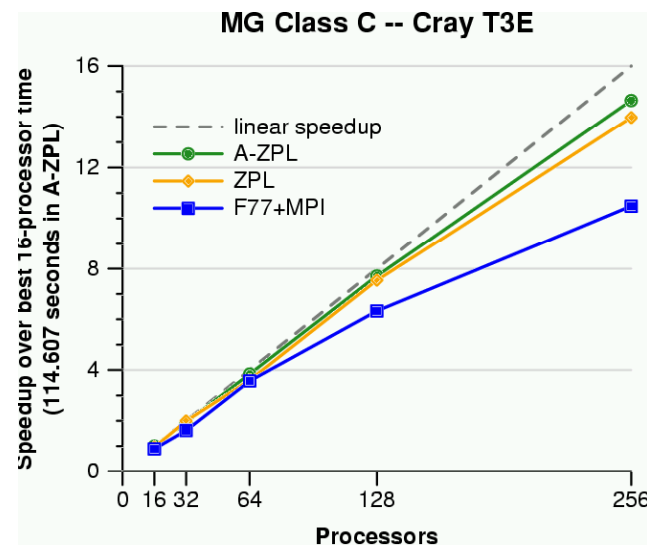
- **Models & Benchmarks**

- **Schedule and Summary**

Analysis of existing codes used to test metrics and identify important trends in productivity and performance

MG Performance

MG Class C -- Cray T3E
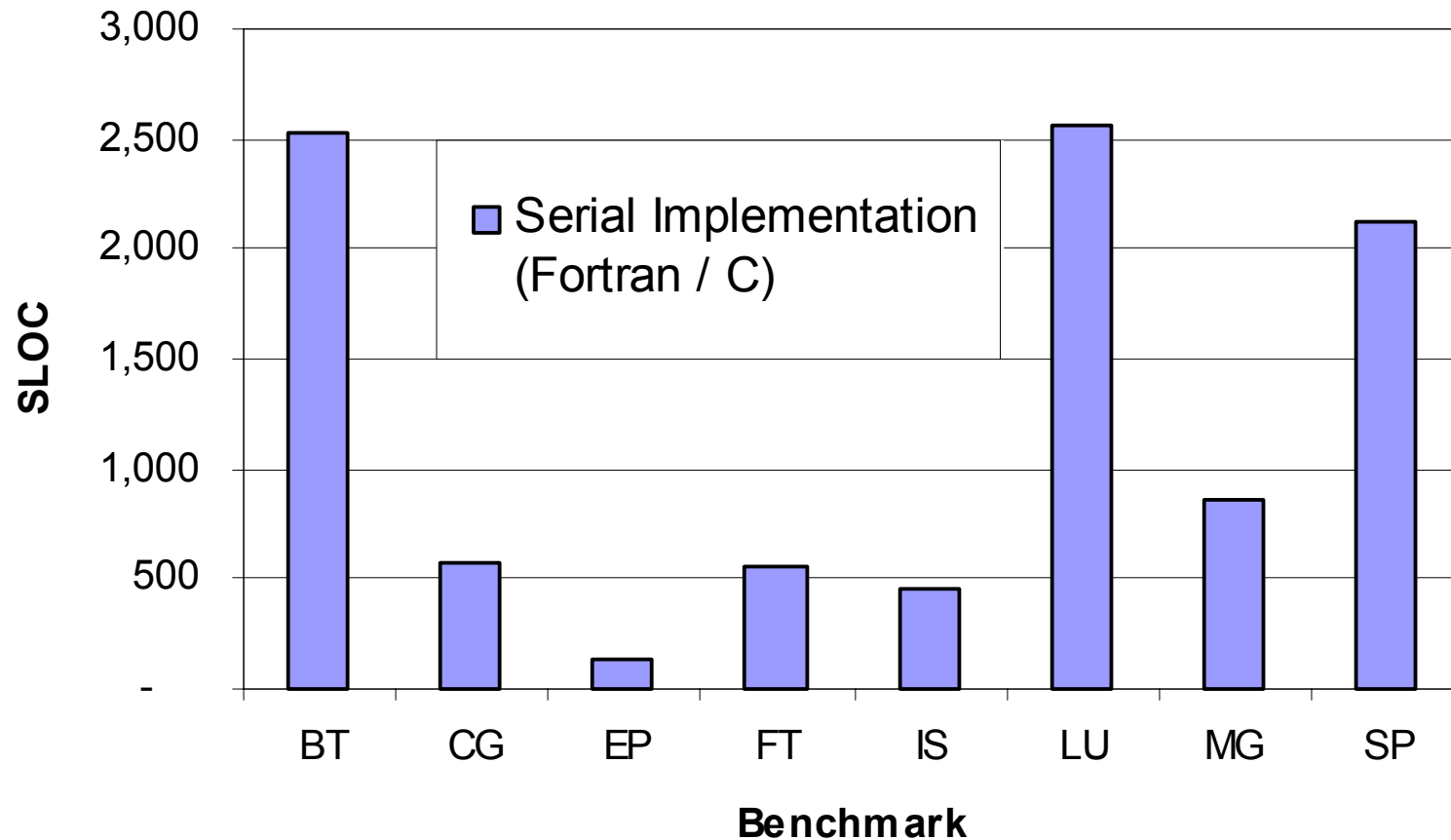

Speedup over best 16-processor time (114.607 seconds in A-ZPL)

- linear speedup
- A-ZPL
- ZPL
- F77+MPI

Processors

NAS MG Linecounts

- comm/sync/dir
- declarations
- computation

MPI Java HPF OpenMP Serial A-ZPL

NPB Implementations

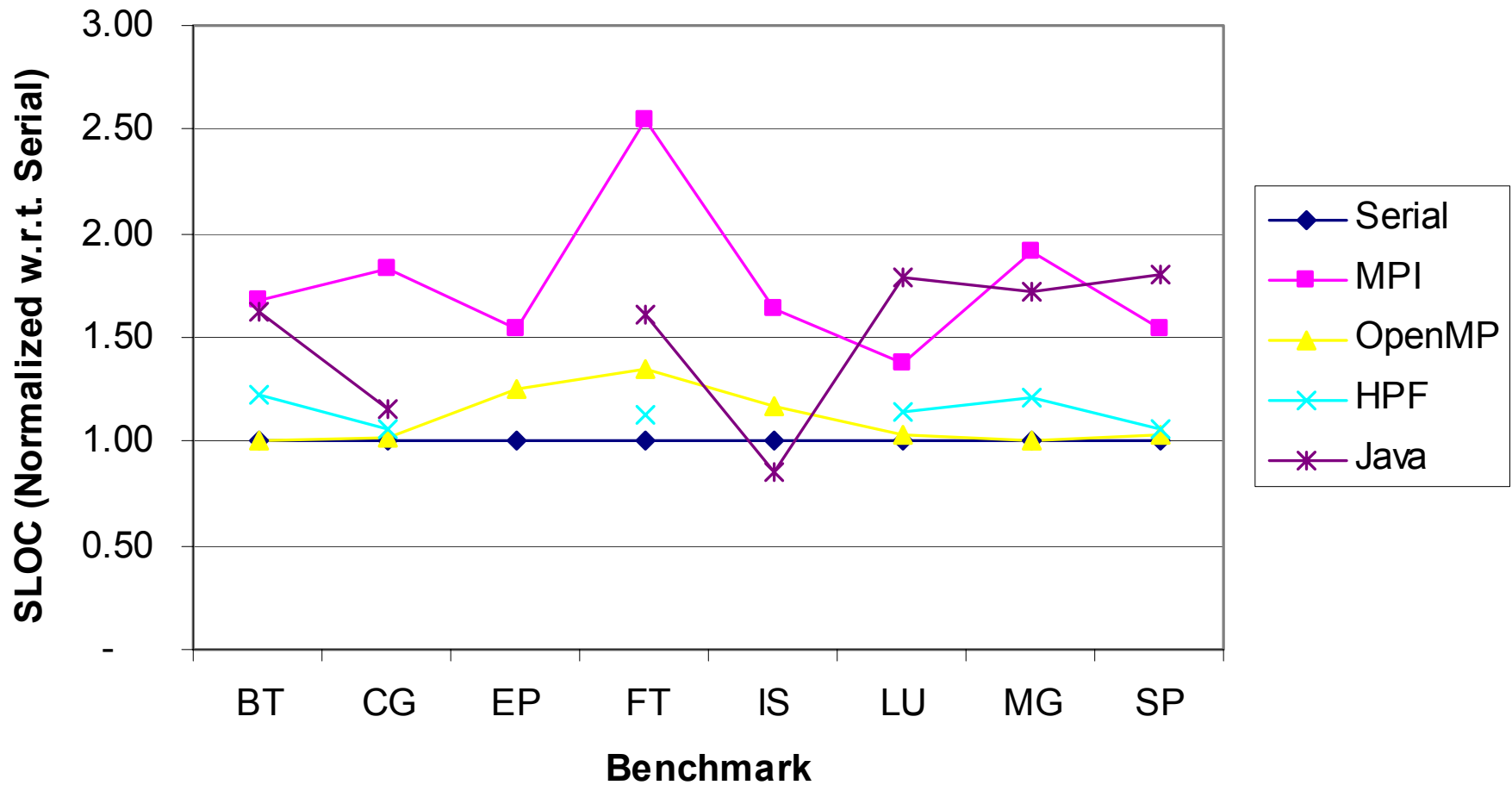| Benchmark	Languages							
	Serial Fortran	Serial C	Fortran / MPI	C / MPI	Fortan / OpenMP	C / OpenMP	HPF	Java
BT	🟩		🟩		🟩		🟩	🟩
CG	🟩		🟩		🟩		🟩	🟩
EP	🟩		🟩		🟩			
FT	🟩		🟩		🟩		🟩	🟩
IS		🟩		🟩		🟩		🟩
LU	🟩		🟩		🟩		🟩	🟩
MG	🟩		🟩		🟩		🟩	🟩
SP	🟩		🟩		🟩		🟩	🟩

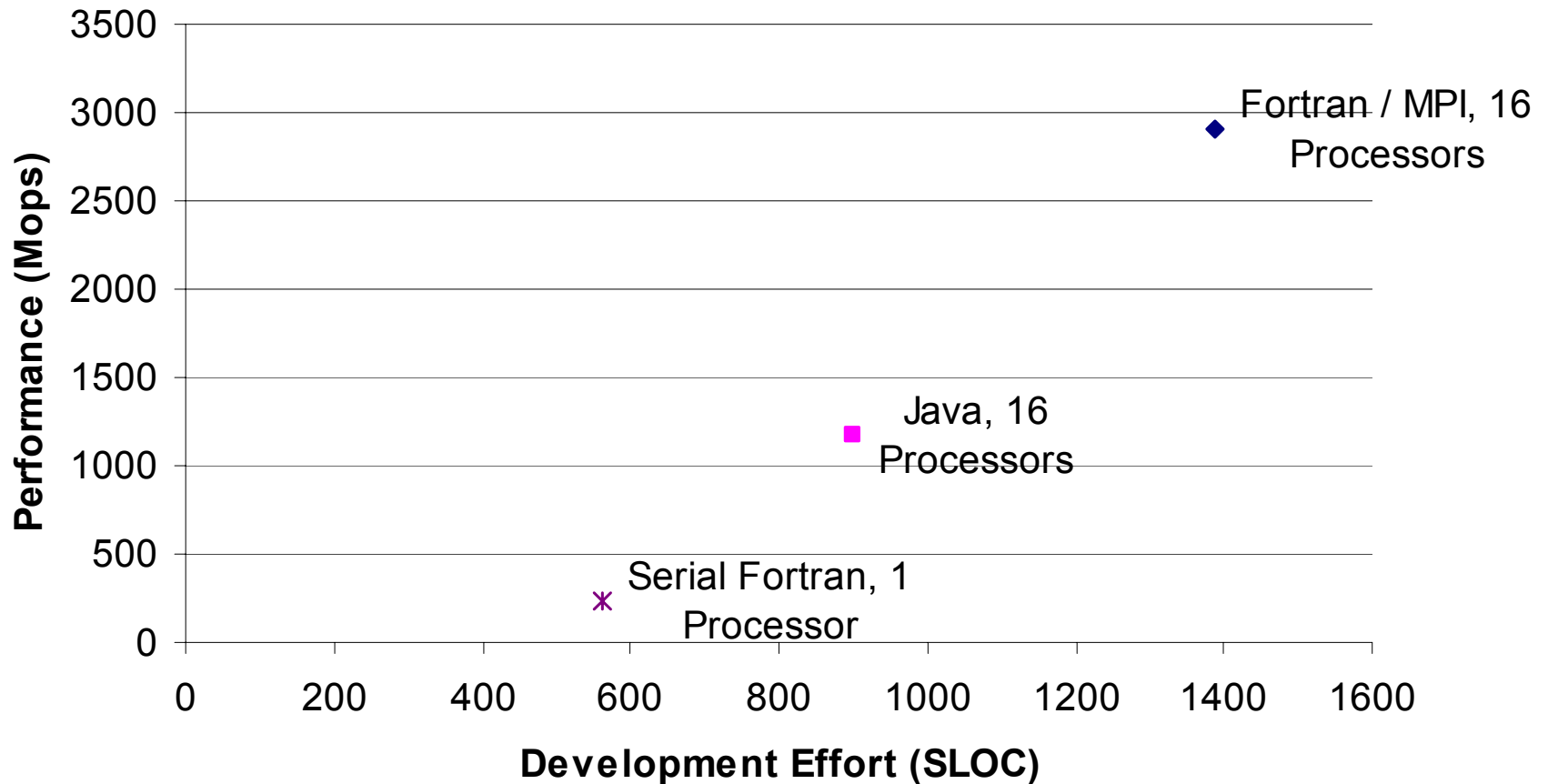# Source Lines of Code (SLOC) for the NAS Parallel Benchmarks (NPB)

Normalized SLOC for
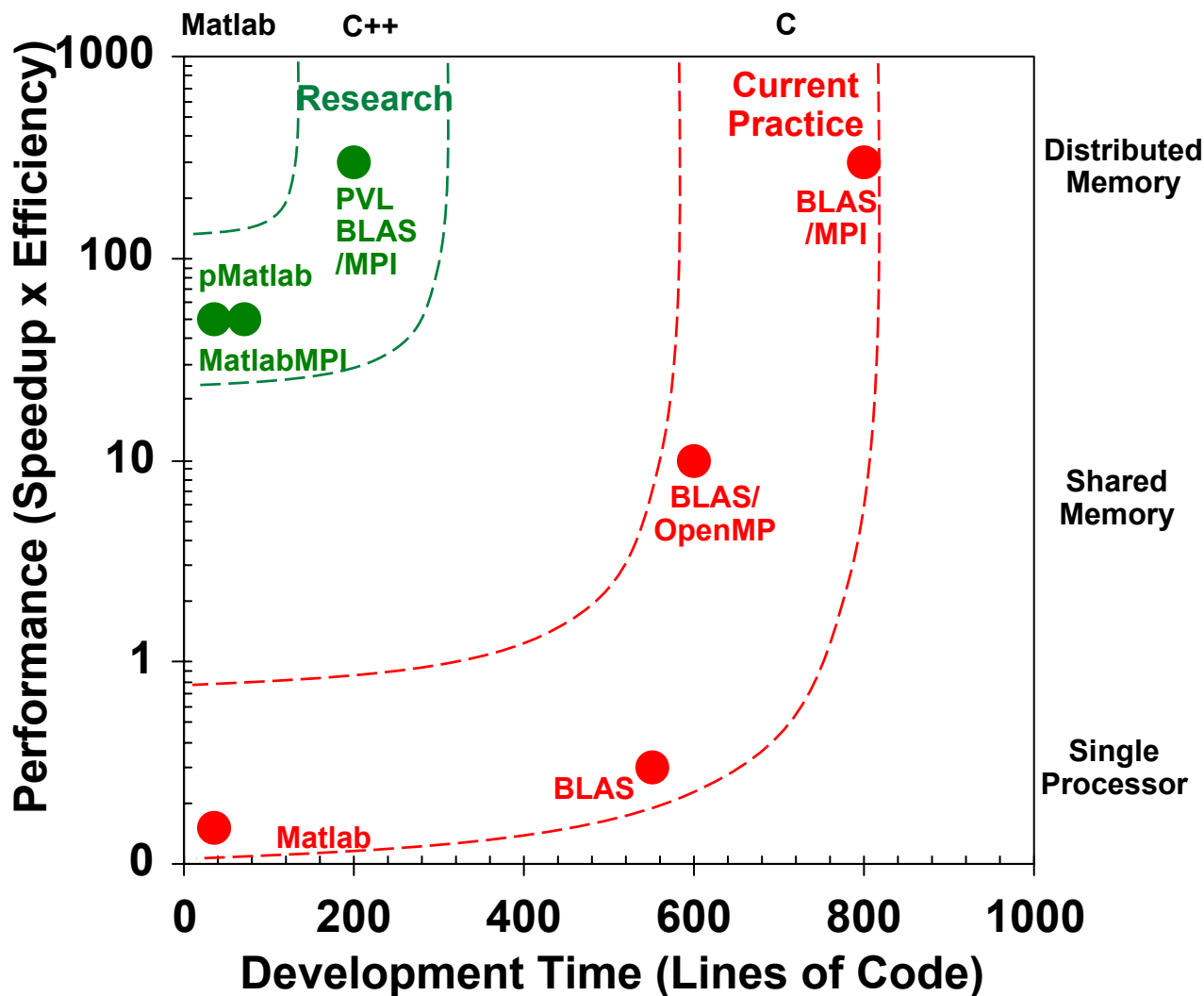# All Implementations of the NPB

NAS FT Performance vs. SLOCs
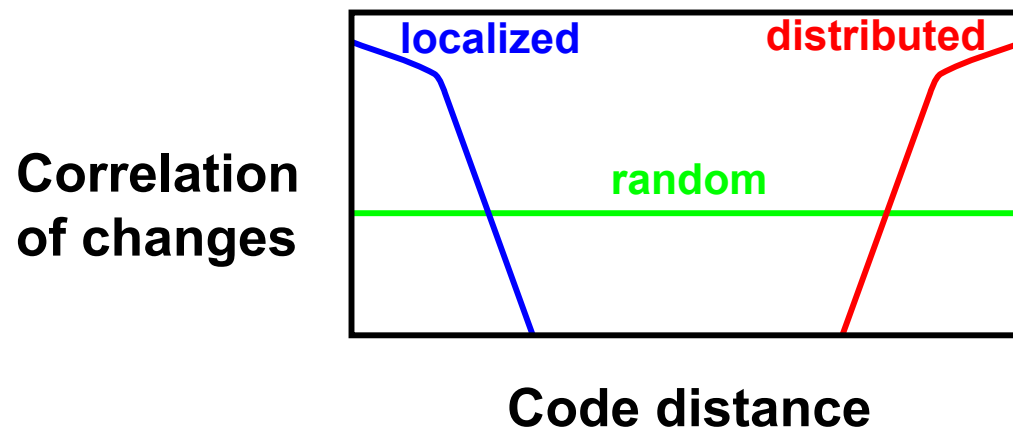
Example Experiment Results (N=1)

- **Same application (image filtering)**
- **Same programmer**
- **Different langs/libs**
  - **Matlab**   *Estimate
  - **BLAS**
  - **BLAS/OpenMP**
  - **BLAS/MPI***
  - **PVL/BLAS/MPI***
  - **MatlabMPI**
  - **pMatlab***

Chart axes: Performance (Speedup x Efficiency) vs Development Time (Lines of Code)

Labels on chart: Matlab, C++, C, Research, Current Practice, PVL BLAS /MPI, pMatlab, MatlabMPL, BLAS/MPI, BLAS/ OpenMP, BLAS, Matlab, Distributed Memory, Shared Memory, Single Processor

Controlled experiments can potentially measure the impact of different technologies and quantify development time and execution time tradeoffs

Novel Metrics

- **HPC Software Development often involves changing code ($\triangle x$) to change performance ($\triangle y$)**
  - **1st order size metrics measures scale of change $E(\triangle x)$**
  - **2nd order metrics would measure nature of change $E(\triangle x^2)$**

- **Example: 2 Point Correlation Function**
  - **Looks at "distance" between code changes**
  - **Determines if changes are localized (good) or distributed (bad)**

Correlation of changes

localized   distributed

random

Code distance
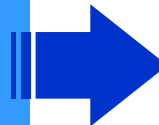
- **Other Zany Metrics**
  - **See Cray talk**

Outline

- **Introduction**

- **Workflows**

- **Metrics**

- **Models & Benchmarks** → • *Prototype Models*
  - *A&P Benchmarks*

- **Schedule and Summary**

Special Model with Work Estimator (Sterling)

$$\Psi_w = \frac{S_P \times E \times A}{c_f \times \left\{ \Gamma \times \left(\overline{\rho} \bullet \overline{n} \right) \right\} + \left(c_m + c_o \right) \times T}$$

Utility (Snir)

$$P(S, A, U(.)) = \min_{\cos t} \frac{U(T(S, A, Cost))}{Cost}$$

Productivity Factor Based (Kepner)

$$productivity_{\substack{GUPS \\ \cdots \\ Linpack}} \approx \left(\frac{\left(\frac{useful\ ops}{second} \right)_{\substack{GUPS \\ \cdots \\ Linpack}}}{Hardware\ Cost} \right) \left(\substack{productivity \\ factor} \right) \left(\substack{mission \\ factor} \right)$$

$$\left(\substack{productivity \\ factor} \right) \approx \left(\substack{Language \\ Level} \right) \times \left(\substack{Parallel \\ Model} \right) \times Portability \times \frac{Availability}{Maintenance}$$
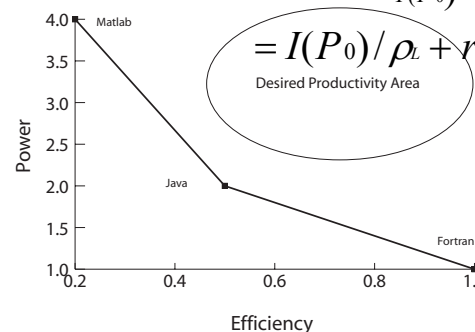
Efficiency and Power (Kennedy, Koelbel, Schreiber)

$$T(P_L) = I(P_L) + rE(P_L)$$

$$= I(P_0) \cdot \frac{I(P_L)}{I(P_0)} + rE(P_0) \cdot \frac{E(P_L)}{E(P_0)}$$
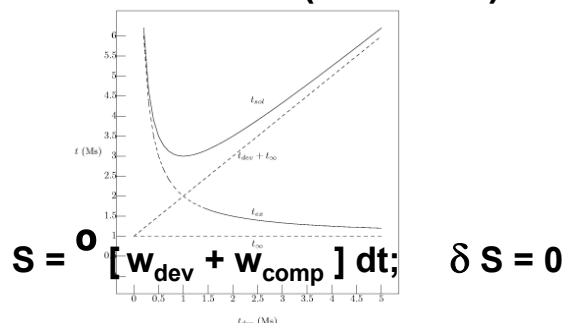
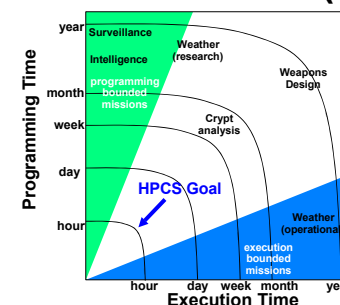$$= I(P_0)/\rho_L + rE(P_0)/\varepsilon_L$$

Desired Productivity Area

(plot: Power vs Efficiency; points labeled Matlab, Java, Fortran)

CoCoMo II (software engineering community)

$$\left(\substack{Effort \\ Multipliers} \right) \times A \times \left(Size \right)^{\left(\substack{Scale \\ Factors} \right)}$$

Least Action (Numrich)

$$S = \int^{o} \left[w_{dev} + w_{comp} \right] dt; \quad \delta S = 0$$

Time-To-Solution (Kogge)

(plot: Programming Time vs Execution Time; regions labeled Surveillance, Intelligence, Weather (research), Weapons Design, Crypt analysis, programming bounded missions, HPCS Goal, Weather (operational), execution bounded missions)

HPCS has triggered ground breaking activity in understanding HPC productivity
-Community focused on *quantifiable* productivity (potential for broad impact)
-Numerous proposals provide a strong foundation for Phase 2

Code Size and Reuse Cost

Lines of code
Function Points
Reuse
Re-engineering
Maintenance

$$\text{Code Size} = \left[\text{New}\right] + \left[\text{Reused}\right] + \left[\text{Re-engineered}\right] + \left[\text{Maintained}\right]$$

Measured in lines of code or functions points (converted to lines of code)

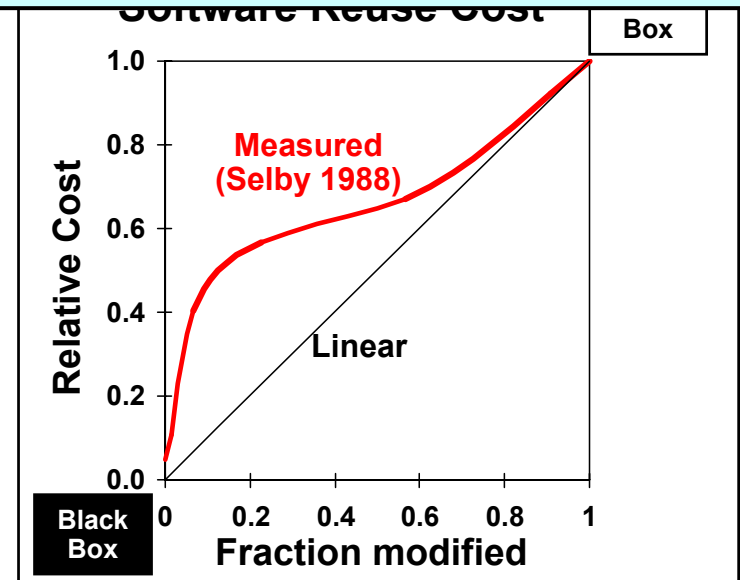| Lines per function point	
C, Fortran	~100
Fortran77	~100
C++	~30
Java	~30
Matlab	~10
Python	~10
Spreadsheet	~5

HPC Challenge Areas

Function Points
High productivity languages not available on HPC

Reuse
Nonlinear reuse effects. Performance requirements dictate "white box" reuse model

- **Code size is the most important software productivity parameter**

- **Non-HPC world reduces code size by**
  - **Higher level languages**
  - **Reuse**

- **HPC performance requirements currently limit the exploitation of these approaches**

Software Reuse Cost

Black Box

Box

Measured (Selby 1988)

Linear

Relative Cost

Fraction modified

Activity & Purpose Benchmarks

Activity & Purpose Benchmark

Development Workflow

Activity Benchmarks define a set of instructions (i.e., source code) to be executed
Purpose Benchmarks define requirements, inputs and output
Together they address the entire development workflow

HPCS Phase 1 Example Kernels and Applications

Mission Area	Kernels	Application	Source
Stockpile Stewardship	Random Memory Access	UMT2000	ASCI Purple Benchmarks
	Unstructured Grids		
	Eulerian Hydrocode	SAGE3D	ASCI Purple Benchmarks
	Adaptive Mesh		
	Unstructured Finite Element Model	ALEGRA	Sandia National Labs
	Adaptive Mesh Refinement		
Operational Weather and Ocean Forecasting	Finite Difference Model	NLOM	DoD HPCMP TI-03
Army Future Combat Weapons Systems	Finite Difference Model	CTH	DoD HPCMP TI-03
	Adaptive Mesh Refinement		
Crashworthiness Simulations	Multiphysics Nonlinear Finite Element	LS-DYNA	Available to Vendors

	Kernels	Application	Source
Other Kernels	Lower / Upper Triangular Matrix Decomposition	LINPACK	Available on Web
	Conjugate Gradient Solver		DoD HPCMP TI-03
	QR Decomposition		Paper & Pencil for Kernels
	1D FFT		Paper & Pencil for Kernels
	2D FFT		Paper & Pencil for Kernels
	Table Toy (GUP/s)		Paper & Pencil for Kernels
	Multiple Precision Mathematics		Paper & Pencil for Kernels
	Dynamic Programming		Paper & Pencil for Kernels
	Matrix Transpose [Binary manipulation]		Paper & Pencil for Kernels
	Integer Sort [With large multiword key]		Paper & Pencil for Kernels
	Binary Equation Solution		Paper & Pencil for Kernels
	Graph Extraction (Breadth First) Search		Paper & Pencil for Kernels
	Sort a large set		Paper & Pencil for Kernels
	Construct a relationship graph based on proximity		Paper & Pencil for Kernels
	Various Convolutions		Paper & Pencil for Kernels
	Various Coordinate Transforms		Paper & Pencil for Kernels
	Various Block Data Transfers		Paper & Pencil for Kernels

Bio-Application	Kernels	Application	Source
Quantum and Molecular Mechanics	Macromolecular Dynamics	CHARMM	http://yuri.harvard.edu/
	Energy Minimization		
	MonteCarlo Simulation		
Whole Genome Analysis	Sequence Comparison	Needleman-Wunsch	http://www.med.nyu.edu/rcr/rcr/course/sim-sw.html
		BLAST	http://www.ncbi.nlm.nih.gov/BLAST/
		FASTA	http://www.ebi.ac.uk/fasta33/
		HMMR	http://hmmer.wustl.edu/
Systems Biology	Functional Genomics	BioSpice (Arkin, 2001)	http://genomics.lbl.gov/~aparkin/Group/Codebase.html
	Biological Pathway Analysis		

Set of scope benchmarks representing Mission Partner and emerging Bio-Science high-end computing requirements

- **Introduction**

- **Workflows**

- **Metrics**

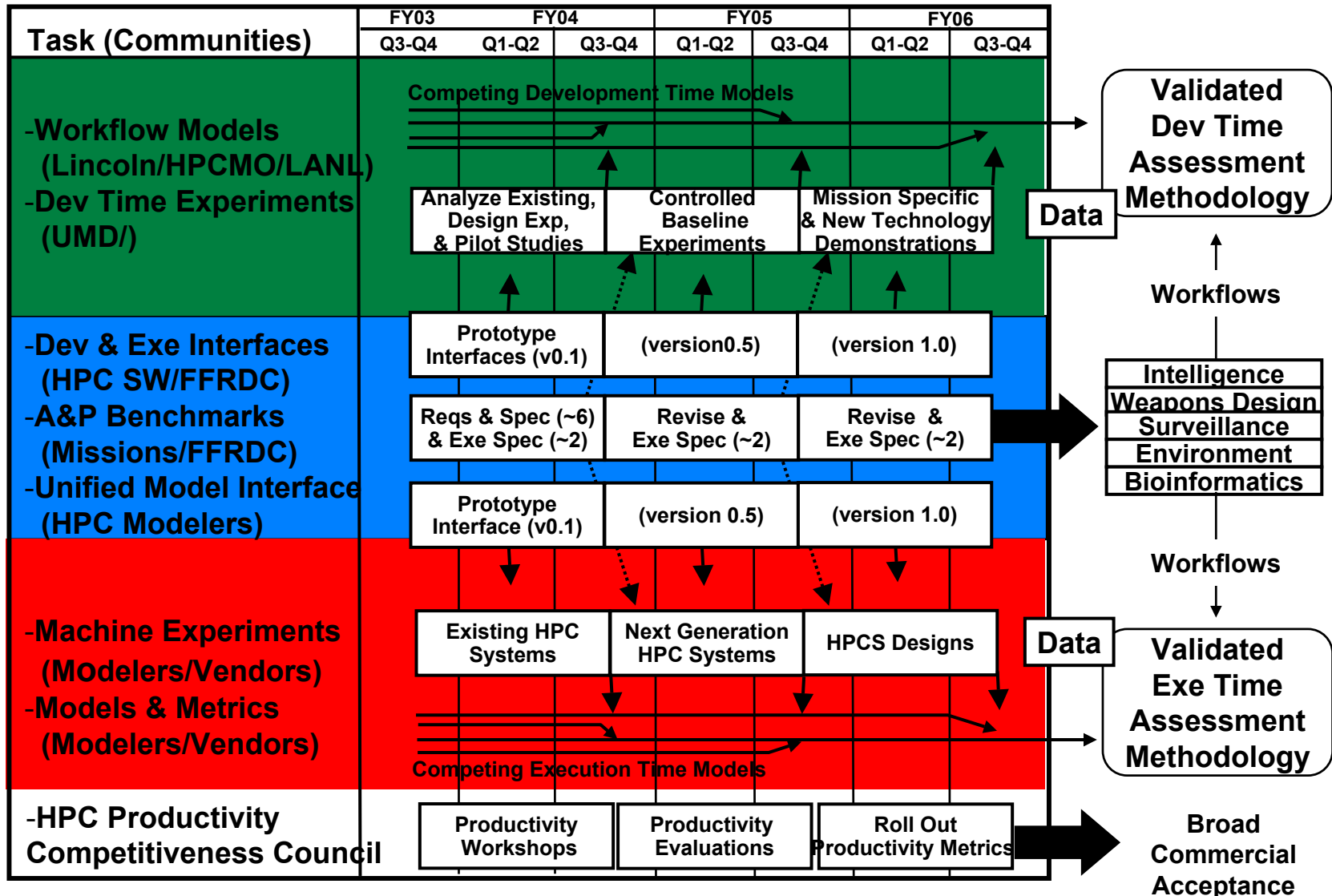- **Models & Benchmarks**

- **Schedule and Summary**

Phase II Productivity Forum Tasks and Schedule

Summary

- **Goal is to develop an acquisition quality framework for HPC systems that includes**
  - **Development time**
  - **Execution time**

- **Have assembled a team that will develop models, analyze existing HPC codes, develop tools and conduct HPC development time and execution time experiments**

- **Measures of success**
  - **Acceptance by users, vendors and acquisition community**
  - **Quantitatively explain HPC rules of thumb:**
    - **"OpenMP is easier than MPI, but doesn't scale a high"**
    - **"UPC/CAF is easier than OpenMP"**
    - **"Matlab is easier the Fortran, but isn't as fast"**
  - **Predict impact of new technologies**

Backup Slides

MITRE   MIT Lincoln Laboratory   ISI
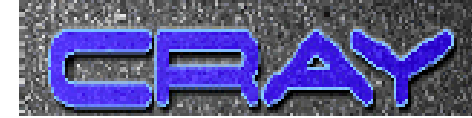
HPCS Phase II Teams

Industry:

PI: Elnozahy   PI: Gustafson   PI: Smith

Goal:

➤ **Provide a new generation of economically viable high productivity computing systems for the national security and industrial user community (2007 – 2010)**

Productivity Team (Lincoln Lead)

MIT Lincoln Laboratory

PI: Kepner   PI: Lucas   PI: Basili   PI: Benson & Snavely

MITRE   Los Alamos NATIONAL LABORATORY   ARGONNE   BERKELEY LAB   UCSB   LCS   Ohio State   CODESOURCERY

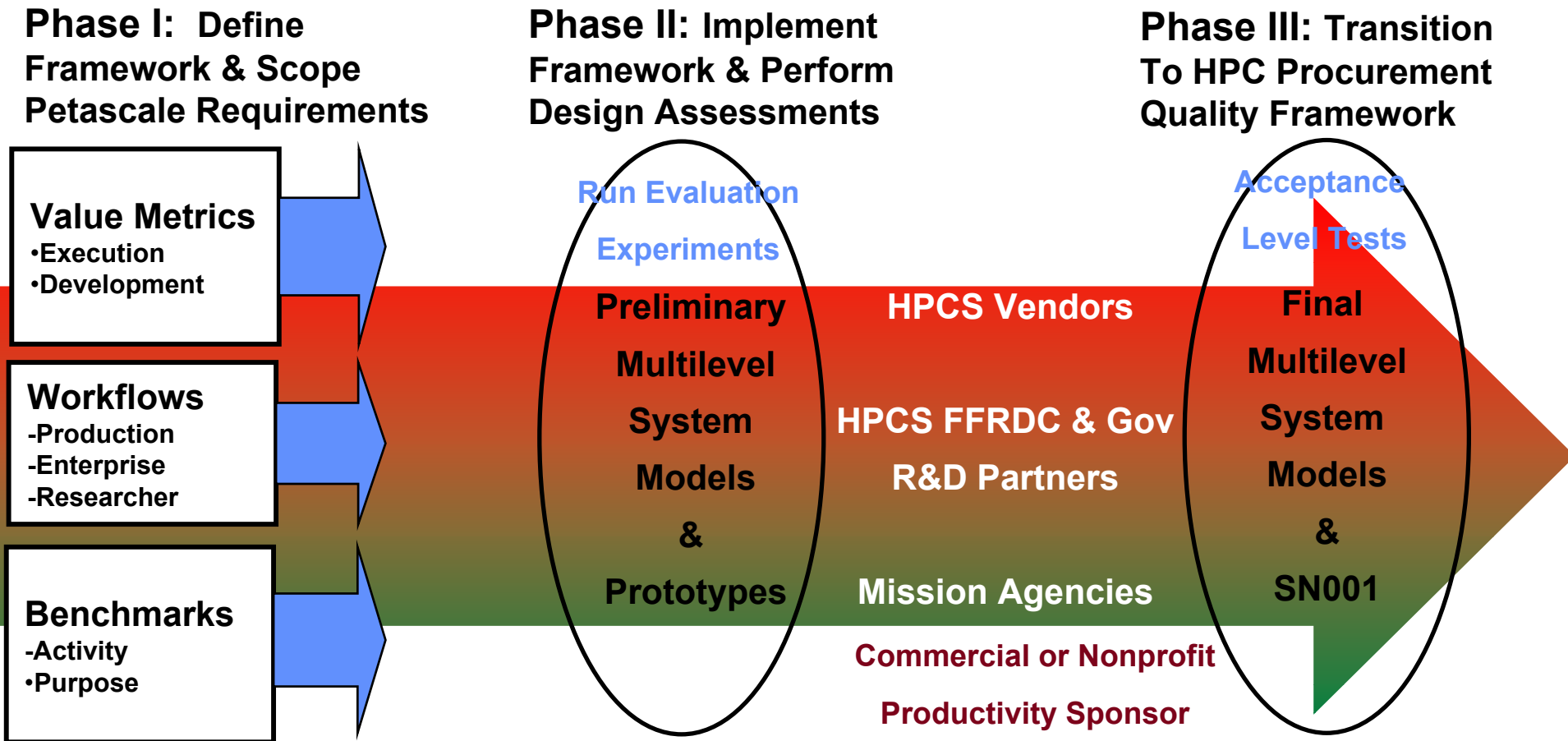PI: Koester   PIs: Vetter, Lusk, Post, Bailey   PIs: Gilbert, Edelman, Ahalt, Mitchell

Goal:

➤ **Develop a procurement quality assessment methodology that will be the basis of 2010+ HPC procurements**

Productivity Framework Overview

Phase I: Define Framework & Scope Petascale Requirements

Phase II: Implement Framework & Perform Design Assessments

Phase III: Transition To HPC Procurement Quality Framework

Value Metrics
- Execution
- Development

Workflows
- Production
- Enterprise
- Researcher

Benchmarks
- Activity
- Purpose

Run Evaluation Experiments

Preliminary Multilevel System Models & Prototypes

HPCS Vendors

HPCS FFRDC & Gov R&D Partners

Mission Agencies

Commercial or Nonprofit Productivity Sponsor

Acceptance Level Tests

Final Multilevel System Models & SN001

HPCS needs to develop a procurement quality assessment methodology that will be the basis of 2010+ HPC procurements

MITRE — MIT Lincoln Laboratory — ISI